Foams, Polytopes, Abstract Tensors, and Homology

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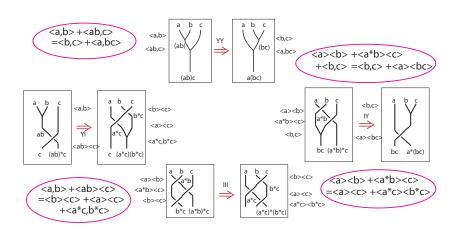
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- 5. Current funding: Simons Foundation.



Section 1

in which systems of abstract tensor equations are formulated and a solution is proposed.

3D moves



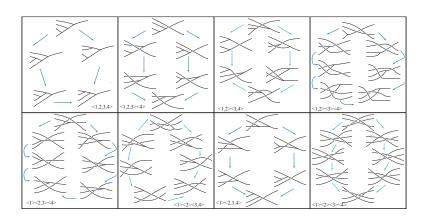
In 3-D equations

$$\begin{array}{|c|c|} \hline \textbf{A} & \textbf{Y}_{j}^{\ell,n}\textbf{Y}_{i}^{j,k} = \textbf{Y}_{p}^{n,k}\textbf{Y}_{i}^{\ell,p} \\ \textbf{YI} & \textbf{Y}_{d}^{a,b}\textbf{X}_{e,f}^{d,c} = \textbf{X}_{c,h}^{b,c}\textbf{X}_{e,g}^{a,c}\textbf{Y}_{f}^{g,h}. \\ \textbf{IY} & \textbf{X}_{d,g}^{a,b}\textbf{X}_{h,f}^{g,c}\textbf{Y}_{e}^{d,h} = \textbf{Y}_{i}^{b,c}\textbf{X}_{e,f}^{a,i}. \\ \textbf{III} & \textbf{X}_{d,e}^{a,b}\textbf{X}_{i,h}^{e,c}\textbf{X}_{f,g}^{d,i} = \textbf{X}_{j,k}^{b,c}\textbf{X}_{f,e}^{a,j}\textbf{X}_{g,h}^{e,k} \\ \hline \end{array}$$

Easy Solution

$$\begin{aligned} \mathsf{Y}^{a,b}_c &= \left\{ \begin{array}{ll} 1 & \text{if } c = ab, \\ 0 & \text{otherwise;} \end{array} \right. \\ \mathsf{X}^{a,b}_{c,d} &= \left\{ \begin{array}{ll} 1 & \text{if } c = b \ \& \ d = b^{-1}ab, \\ 0 & \text{otherwise.} \end{array} \right. \end{aligned}$$

4D moves



4-D Equations

YYY	$K^{m,n}_{p,q}K^{p,r}_{s,t}=K^{n,r}_{u,v}K^{m,u}_{s,w}K^{w,v}_{t,q}$
YYI	$M^{p,q}_{t,u,v}M^{u,r}_{x,y,z}K^{t,x}_{m,n}=K^{q,r}_{s,i}M^{p,s}_{m,y,j}M^{j,i}_{n,z,v}$
YY	$W_{i,j}^{p,q,r}M_{m,n,y}^{i,s}=M_{t,u,v}^{r,s}M_{m,x,z}^{q,t}W_{n,h}^{p,x,u}W_{y,i}^{h,z,v}$
YII	$\left \begin{array}{c} \mathbf{X}_{t,x,v}^{p,q,r} \mathbf{M}_{y,u,v}^{x,s} \mathbf{M}_{m,n,z}^{t,i} = \mathbf{M}_{j,x,g}^{r,s} \mathbf{M}_{m,t,x}^{q,j} \mathbf{X}_{n,y,f}^{p,t,x} \mathbf{X}_{z,u,v}^{f,w,g} \end{array} \right $
IYY	$K^{p,q}_{u,v}W^{v,r,s}_{i,j}W^{u,i,t}_{y,z} = W^{q,s,t}_{u,v}W^{p,r,u}_{y,i}K^{i,v}_{z,j}$
IYI	$\left M_{u,v,x}^{p,q} X_{i,j,n}^{x,r,s} X_{h,g,f}^{v,j,t} W_{y,z}^{u,i,h} = W_{u,v}^{q,s,t} X_{y,i,j}^{p,r,u} M_{z,f,n}^{j,v} \right $
IIY	$ \left \begin{array}{c} W_{h,j}^{p,q,r} W_{i,n}^{j,s,t} X_{x,y,z}^{h,i,u} = X_{v,g,f}^{r,t,u} X_{x,h,j}^{q,s,v} W_{y,i}^{p,h,g} W_{z,n}^{i,j,f} \end{array} \right $
IIII	$\left \begin{array}{c} \mathbf{X}_{v,x,y}^{p,q,r} \mathbf{X}_{z,e,n}^{y,s,t} \mathbf{X}_{k,h,j}^{x,e,u} \mathbf{X}_{g,f,i}^{v,z,k} = \mathbf{X}_{k,z,v}^{r,t,u} \mathbf{X}_{g,e,x}^{q,s,k} \mathbf{X}_{f,h,y}^{p,e,z} \mathbf{X}_{i,j,n}^{y,x,v} \end{array} \right $

$$\mathsf{K}^{p,q}_{r,s} = \left\{ \begin{array}{l} 1 \text{ if } \exists \ a,b,c \text{ s.t.} \\ p = ((ab,c),0|0), \quad q = ((a,b),0|0), \\ r = ((a,bc),0|0), \& \ s = ((b,c),0|0). \\ 0 \text{ otherwise;} \end{array} \right.$$

$$\mathsf{M}^{i,j}_{p,q,r} = \left\{ \begin{array}{l} 1 \text{ if } \exists \ a,b,c \text{ s.t.} \\ i = ((0,0),ab|c), \quad j = ((a,b),0|0), \\ p = ((a,b) \lhd c,0|0), \quad q = ((0,0),a|c), \\ \& \ r = ((0,0),b|c), \\ 0 \text{ otherwise;} \end{array} \right.$$

$$\mathsf{W}_{p,q}^{i,j,\ell} = \left\{ \begin{array}{l} 1 \text{ if } \exists \ a,b,c \text{ s.t.} \\ i = ((b,c),0|0), \quad j = ((0,0),(a \lhd b)|c), \\ \ell = ((0,0),a|b), \\ p = ((0,0),a|(bc)), \quad \& \ q = ((b,c),0|0), \\ 0 \text{ otherwise;} \end{array} \right.$$

$$\mathbf{X}_{s,t,u}^{p,q,r} = \begin{cases} 1 \text{ if } \exists \ a,b,c \text{ s.t.} \\ p = ((0,0),b|c), \quad q = ((0,0),(a \triangleleft b)|c), \\ r = ((0,0),a|b), \\ s = ((0,0),(a|b) \triangleleft c), \quad t = ((0,0),a|c), \\ \& \ u = ((0,0),b|c), \\ 0 \text{ otherwise;} \end{cases}$$

where, e.g., $a \triangleleft c = c^{-1}ac$, $(a, b) \triangleleft c = (a \triangleleft c, b \triangleleft c)$, and $(a|b) \triangleleft c = (a \triangleleft c)|(b \triangleleft c)$

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So when I write, e.g.

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the tensor M is a morph.

$$V \otimes V \xleftarrow{\mathsf{M}} V \otimes V \otimes V.$$

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,

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$$V \otimes V \otimes V \xleftarrow{\mathsf{W}} V \otimes V,$$

and

$$V \otimes V \otimes V \xleftarrow{\mathbf{X}} V \otimes V \otimes V.$$

I soon want to given the geometric background for these equations, and point out that, I soon want to given the geometric background for these equations, and point out that, as usual, I soon want to given the geometric background for these equations, and point out that, as usual, these systems of equations generalize immediately to all dimensions, and in an appropriate algebraic context, we can find solutions.

Section 2

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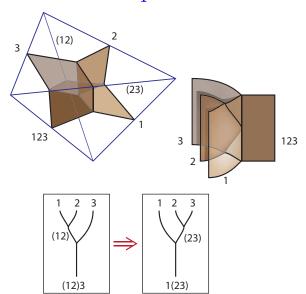
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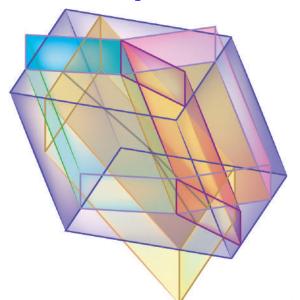
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$$Y^n = C\left(\bigcup_{j=1}^{n+2} Y_j^{n-1}\right).$$

The space Y^2



The space Y^3



Foam Definition

An *n*-dimensional foam is a compact top. sp. X for which each point $x \in X$ has a nbhd. N(x) that is homeom. to a nbhd. M of a point in Y^n .

Local pictures of crossings

Now take

$$\left[\cup_{\ell=1}^k \left(\Delta^{j_1} \times \cdots \times Y^{j_\ell-1} \times \cdots \times \Delta^{j_k} \right) \subset \mathbb{R}^{n+1} \times \{\ell\} \right],$$

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and project this into \mathbb{R}^{n+1} . The factor ℓ is in the (n+2)nd coordinate and represents the relative height of each Y.

$$\left[\left(Y^{j_1-1}\times\Delta^{j_2}\cdots\times\Delta^{j_\ell}\times\cdots\times\Delta^{j_k}\right)\subset\mathbb{R}^{n+1}\times\{1\}\right],$$

$$[(Y^{j_1-1} \times \Delta^{j_2} \cdots \times \Delta^{j_\ell} \times \cdots \times \Delta^{j_k}) \subset \mathbb{R}^{n+1} \times \{1\}],$$
$$[(\Delta^{j_1} \times Y^{j_2-1} \cdots \times \Delta^{j_\ell} \times \cdots \times \Delta^{j_k}) \subset \mathbb{R}^{n+1} \times \{2\}],$$

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These project to a 0-dimensional multiple point in \mathbb{R}^{n+1} .



The local crossings for (n + 1)-foams are found among the Reideimeister/Roseman moves of the embedded n-foams. The local crossings for (n + 1)-foams are found among the Reideimeister/Roseman moves of the embedded n-foams. These crossings are the most homologically interesting aspect of group/quandle homology, as they represent generating chains in the chain groups.

in which a discussion of categorification is used to justify the ideas presented in the previous slide.

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Great invariants for classical knots and knot cobordisms. Not so good for knotted closed surfaces.

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Instead of equality among morphisms, posit 2-morphisms that satisfy their own set of relations.

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Instead of equality among morphisms, posit 2-morphisms that satisfy their own set of relations. Climb the dimension ladder.

Abstract Tensor Formalism Suppose V, W, etc. f.dim'l vec. sp. over $\, \mathbb{F} \! . \,$

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$$\vec{x} = \sum_{j=1}^{n} x^{j} e^{i\vec{x}}$$

Abstract Tensor Formalism

$$\vec{x} = \sum_{j=1}^{n} x^{j} e_{j}$$
 where $e_{j} = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \leftarrow jth$ n rows

so superscripts are row indices.

Abstract

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$$\text{Write} \quad \overrightarrow{x} = \frac{1}{|x|} \quad . \quad \text{If} \quad W \longleftarrow A \quad \text{V} \quad \text{is linear, } A(e_j) = \sum_{i=1}^n a_j^i e_i$$

Write
$$A = A$$
.

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$$T \leftarrow C$$
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Composition of linear maps is denoted by vertical juxtaposition.

$$\mathsf{T} \overset{\mathsf{C}}{\longleftarrow} \mathsf{U} \overset{\mathsf{B}}{\longleftarrow} \mathsf{W} \overset{\mathsf{A}}{\longleftarrow} \mathsf{V} \overset{\mathsf{T}}{\longleftarrow} \mathsf{V}$$

$$\vec{x} = \sum_{j=1}^{n} x^{j} e_{j}$$
 where $e_{j} = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$ $\leftarrow jth$ $\begin{cases} n \text{ rows} \end{cases}$

Abstract

so superscripts are row indices.

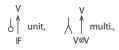
Write
$$\vec{x} = \frac{1}{|x|}$$
. If $W \leftarrow A = V$ is linear, $A(e_j) = \sum_{i=1}^{n} a_j^i e_i$

Write $A = A = A$. So $Ax = b$ is written $A = A = A$.

Composition of linear maps is denoted by vertical juxtaposition.

$$T \overset{C}{\longleftarrow} U \overset{B}{\longleftarrow} W \overset{A}{\longleftarrow} V \overset{I}{\longleftarrow} \overset{T}{\longleftarrow} \overset{S}{\longleftarrow} W \overset{\otimes S}{\longleftarrow} \overset{W \otimes S}{\longleftarrow} \overset{I}{\longleftarrow} \overset{I}$$







$$\bigvee_{i \in I}^{V} \text{unit,} \qquad \bigvee_{V \otimes V}^{V} \text{multi.,} \qquad \bigcap_{V \otimes V}^{IF} \text{non deg. pairing}$$

$$\left| \begin{array}{c} \\ \\ \\ \end{array} \right| = \left| \begin{array}{c} \\ \\ \end{array} \right|$$
 unital axiom

$$\bigvee_{0}^{V} \underset{\text{IF}}{\text{unit}}, \qquad \bigvee_{V \otimes V}^{V} \underset{\text{multi.}}{\text{multi.}}, \qquad \bigcap_{V \otimes V}^{\text{IF}} \underset{\text{non deg. pairing}}{\text{non deg. pairing}}$$

$$\bigvee_{i \in \mathbb{F}} \mathsf{Unit}, \qquad \bigvee_{\mathsf{V} \otimes \mathsf{V}} \mathsf{multi.}, \qquad \bigcap_{\mathsf{V} \otimes \mathsf{V}} \mathsf{non\,deg.\,pairing}$$

$$\bigvee_{i \in \mathbb{F}} \mathsf{V} \quad \bigvee_{i \in \mathbb{F}} \mathsf{V} \quad \mathsf{Multi.}, \quad \bigwedge_{i \in \mathbb{F}} \mathsf{Non deg. pairing}$$

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that satisfy:

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We can use \bigcup and \bigcap to define comulti.

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It's remarkable that most of the axiomatics for the alg.coalg str. follows directly from the diagrammatics.

So a Frobenius algebra has a categorical analogue. Just assert the existence of a monoidal category together with maps Y, etc.

• Objects $\leftrightarrow \mathbb{N} = \{0, 1, \ldots\}$ written in unary notation.

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So a Frobenius algebra has a categorical analogue. Just assert the existence of a monoidal category together with maps Y, etc. So let's look at slightly weaker monoidal category.

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but WAIT! Don't assert identities among the 1-morphisms.



Instead, assert the existence of 2-morphisms.

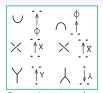
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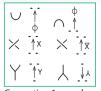
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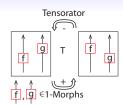
¿Either direction?

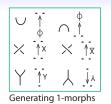


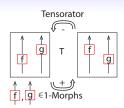
Generating 1-morphs

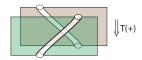


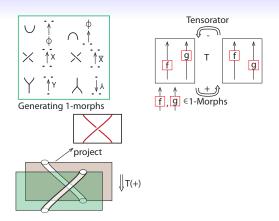
Generating 1-morphs

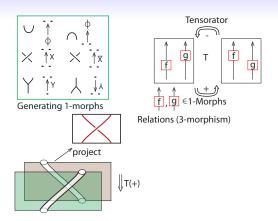


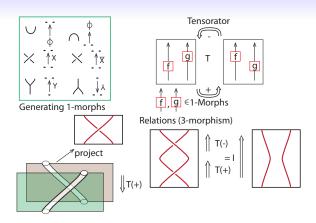


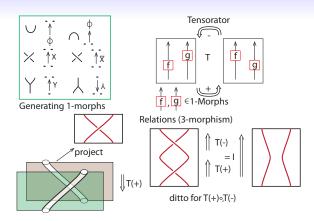


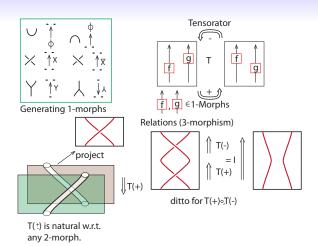


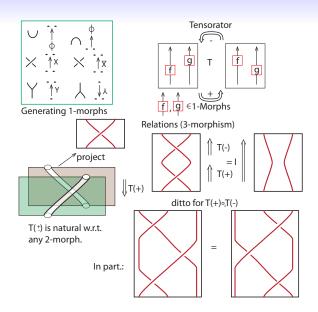


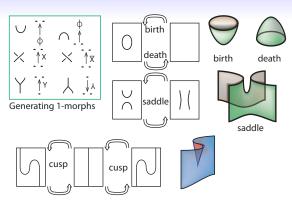








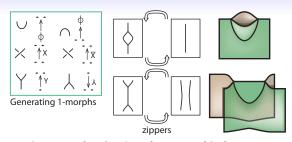




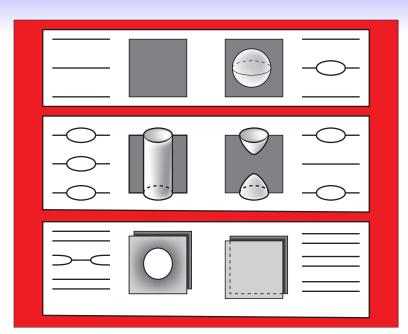
- The critical points evolve to be come folds. (co-oriented away from optimal points)
- Several obvious relations hold among these 2-morphisms.

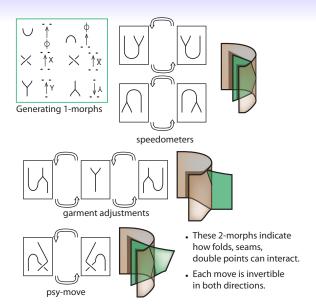
Including • canceling birth/saddle death/saddle

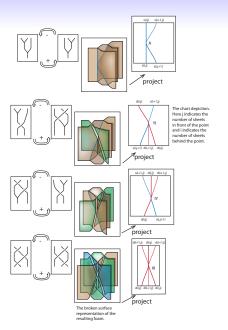
- lips
- beak-to-beak
- swallow-tail
- horizontal cusp

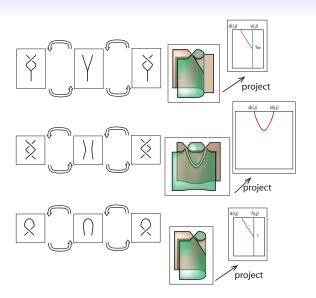


- The vertices of Y or A evolve to form seams of the foam. (co-oriented towards the single sheet)
- There are zig-zag moves that cancel a pair of zipper 2-morphisms.
- Under some circumstances, one might want to suppose bubble and saddle moves hold.
 But, as is the case with birth followd by death, or a pair of opposite saddles, it is better to suppose that the moves in the next slide are some type of 3-morphisms.





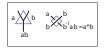


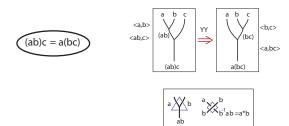


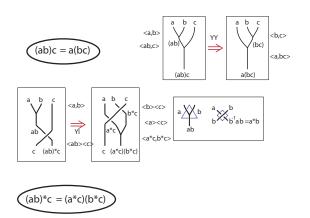
Section 4

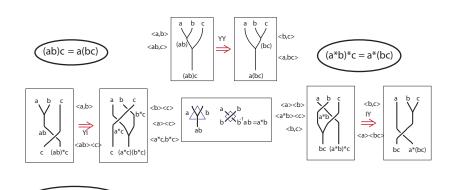
in which an homology theory that encompasses both quandle and group homology is outlined.

Fundamental group



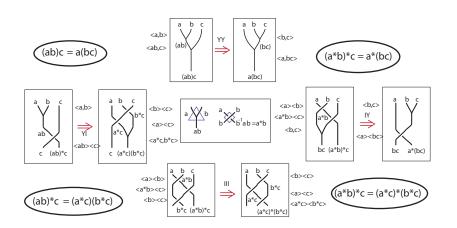






(ab)*c = (a*c)(b*c)





$$\begin{array}{lll} \mathsf{YY} & (ab)c &=& a(bc), \\ \mathsf{IY}: & (ab) \lhd c &=& (a \lhd c)(b \lhd c), \\ \mathsf{YI}: & (a \lhd b) \lhd c &=& a \lhd (bc), \\ \mathsf{III}: & (a \lhd b) \lhd c &=& (a \lhd c) \lhd (b \lhd c). \end{array}$$

A quandle

satisfies three axioms that correspond to the Reidemeister moves:

```
I: \qquad (\forall a): \quad a \triangleleft a = a
II: \qquad (\forall a, b)(\exists c): \quad c \triangleleft b = a
III: \qquad (\forall a, b, c): \quad (a \triangleleft b) \triangleleft c = (a \triangleleft c) \triangleleft (b \triangleleft c).
```

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$$III: \qquad (\forall a, b, c): \quad (a \triangleleft b) \triangleleft c = (a \triangleleft c) \triangleleft (b \triangleleft c).$$

We are interested in how the group G and its associated quandle Conj(G) interact.

There are related concepts for which the homology sketched below applies, e.g.:

• G-families of quandles (IIJO)

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- Lebed's qualgebras

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Here we use, YY, YI, IY, and III to define the homological conditions.

Slicing

Cut the interval [0, n] into integral pieces.

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$$\langle 1, 2, \dots, \ell_1 \rangle \langle \ell_1 + 1, \dots, \ell_1 + \ell_2 \rangle \cdots$$

$$\left\langle \sum_{i=1}^{j-1} \ell_i + 1, \dots, \sum_{i=1}^{j} \ell_i \right\rangle \dots \left\langle \sum_{i=1}^{k} \ell_i + 1, \dots, n \right\rangle.$$

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Such a slice corresponds to a decomposition of the n-ball into a product of simplices. There are 2^{n-1} ways to cut.

$$\partial \langle j+1, j+2, \dots, j+k \rangle$$

$$\partial \langle j+1, j+2, \dots, j+k \rangle$$

= $\langle (j+1)\langle j+2, \dots, j+k \rangle$

$$\begin{split} \partial \langle j+1, j+2, \dots, j+k \rangle \\ &= \langle (j+1)\langle j+2, \dots, j+k \rangle \\ &+ \sum_{k=1}^{k-1} (-1)^{\ell} \langle j+1, \dots, (j+\ell) \cdot (j+\ell+1), \dots, j+k \rangle \end{split}$$

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$$\partial(PQ) = (\partial P)Q + (-1)^{\dim P}P(\partial Q).$$

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In part,

$$\partial \langle j+1 \rangle = \langle (j+1) \cup - \cup.$$

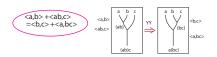


Following Przytycki, one can observe that $\partial \circ \partial = 0$ in this context, if and only if

- $\bullet \ a(bc) = (ab)c$
- $a \triangleleft (bc) = (a \triangleleft b) \triangleleft c$
- $(ab) \triangleleft c = (a \triangleleft c)(b \triangleleft c)$
- $(a \triangleleft b) \triangleleft c = (a \triangleleft c) \triangleleft (b \triangleleft c)$

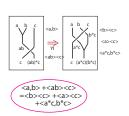
$$\begin{array}{rcl} \partial \langle 1,2,3 \rangle & = & \langle 2,3 \rangle - \langle 1 \cdot 2,3 \rangle \\ & & + \langle 1,2 \cdot 3 \rangle - \langle 1,2 \rangle \end{array}$$

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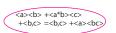
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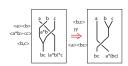
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$$\begin{array}{rcl} \partial \langle 1 \rangle \langle 2, 3 \rangle & = & \langle 2, 3 \rangle - \langle 2, 3 \rangle - \langle 1 \rangle \partial \langle 2, 3 \rangle \\ & = & -\langle 1 \triangleleft 2 \rangle \langle 3 \rangle + \langle 1 \rangle \langle 2 \cdot 3 \rangle - \langle 1 \rangle \langle 2 \rangle \end{array}$$

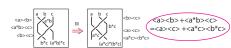
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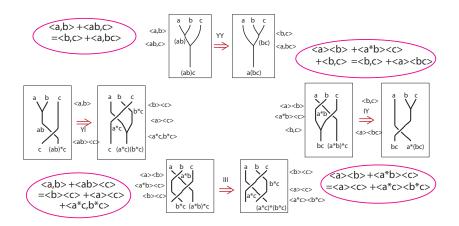




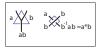
$$\begin{array}{lll} \partial\langle 1\rangle\langle 2\rangle\langle 3\rangle &=& \langle 2\rangle\langle 3\rangle - \langle 2\rangle\langle 3\rangle - \langle 1\rangle\partial(\langle 2\rangle\langle 3\rangle) \\ &=& -\langle 1 \triangleleft 2\rangle\langle 3\rangle + \langle 1\rangle\langle 3\rangle \\ && +\langle 1 \triangleleft 3\rangle\langle 2 \triangleleft 3\rangle - \langle 1\rangle\langle 2\rangle \end{array}$$

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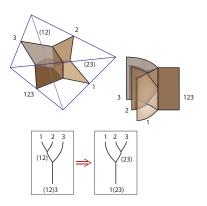




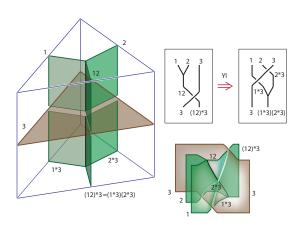
Triangles and Squares



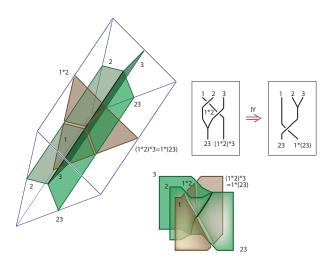
Tetrahedron



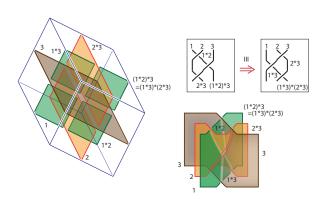
First Prism



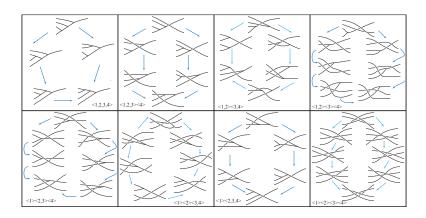
Second Prism



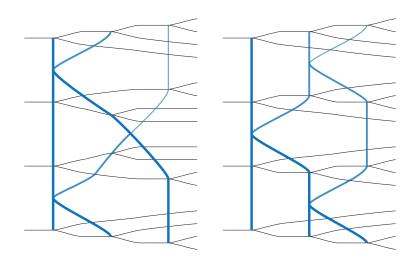
Cube



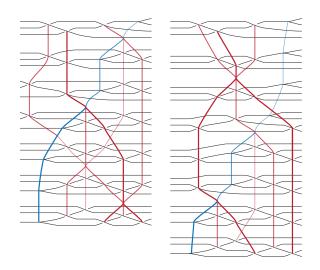
8 interesting moves



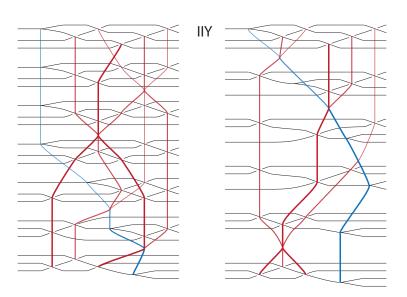
The YYY-move (Stasheff polytope)



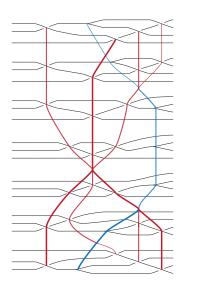
The YII-move

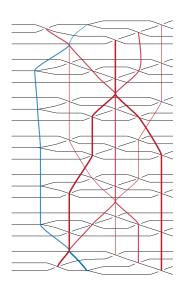


The IIY-move

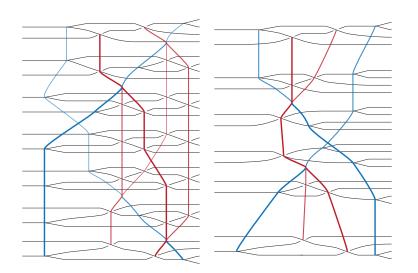


The IYI-move

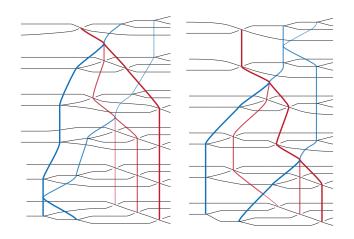




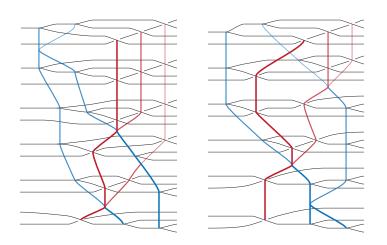
The YY-move



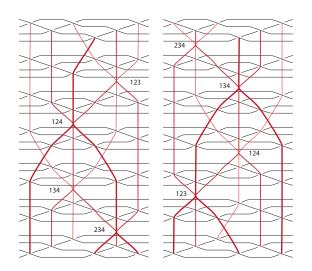
The YYI-move



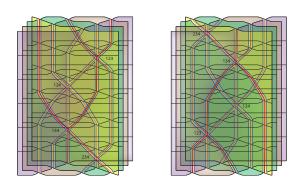
The IYY-move



The tetrahedral-move



The tetrahedral-move



Visual interlude

in which many (not all) of the Reidemeister/Roseman moves for 2-foams are indicated.

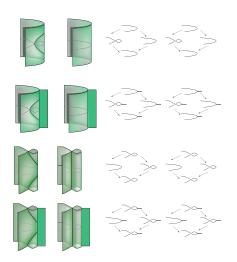
Visual interlude

in which many (not all) of the Reidemeister/Roseman moves for 2-foams are indicated. Categorical hint:

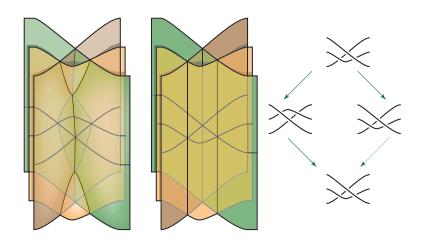
Visual interlude

in which many (not all) of the Reidemeister/Roseman moves for 2-foams are indicated. Categorical hint: when certain 2-morphisms are defined to be invertible, these moves arise.

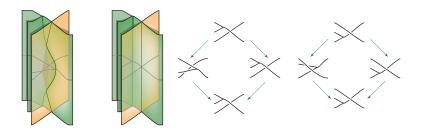
Critical points of the branch point set



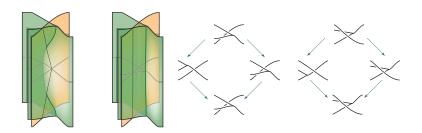
Critical points of the triple point set



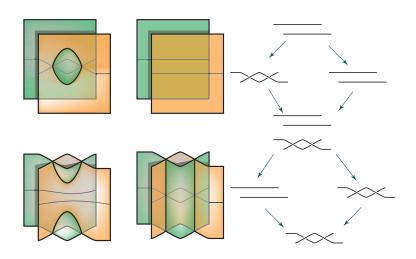
Critical points of the intersection set 1



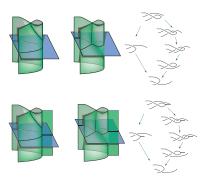
Critical points of the intersection set 2



Critical points of the double point set



Int. pts. b/2 branch/twist set and trnsvs. sheet



Not all 3-morphisms (or identities among 2 morphisms) are listed here.

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The analogues in one higher dimensions

of the generating chains in homology.

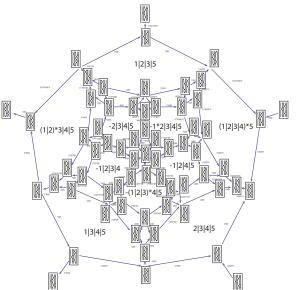
The analogues in one higher dimensions

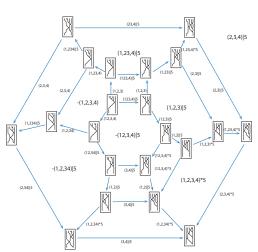
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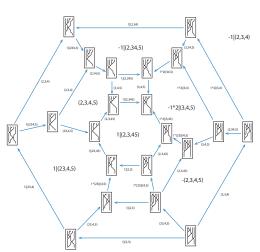
The analogues in one higher dimensions

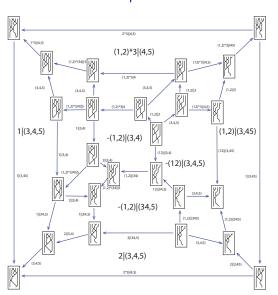
of the generating chains in homology. One bit of the visual interlude is finished, but I want to astound you a little more.

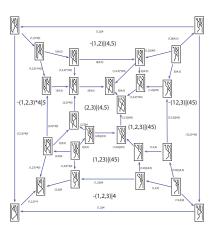
1|2|3|4|5



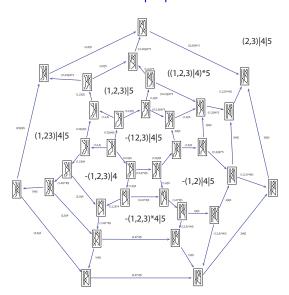




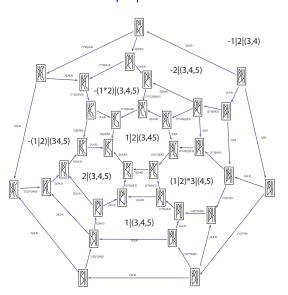




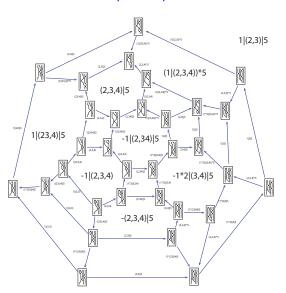
123|4|5



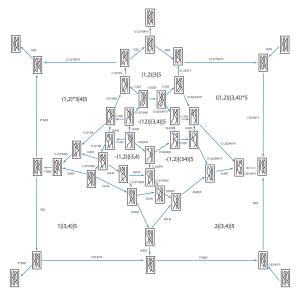
1|2|345



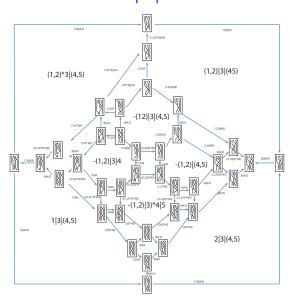
1|234|5



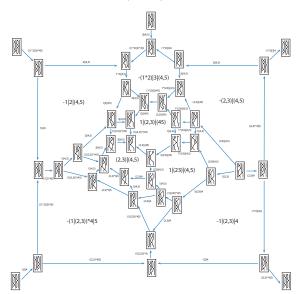
12|34|5



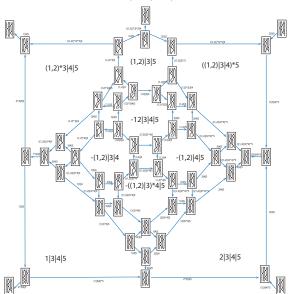
12|3|45



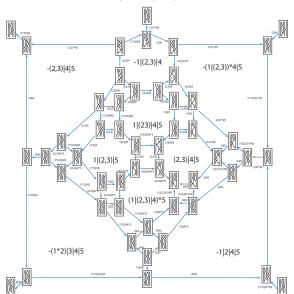
1|23|45



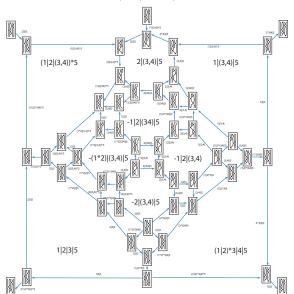
12|3|4|5



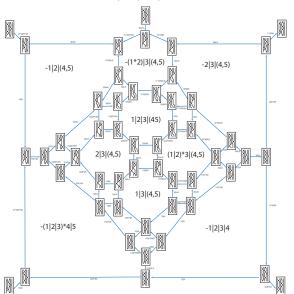
1|23|4|5

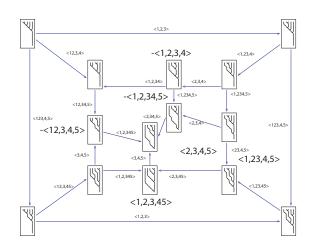


1|2|34|5



1|2|3|45





Section 5

in which the polytopal duals to the generating chains are formulated.

In this section, I am going to review something that is

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In \mathbb{R}^n consider the convex hull of

$$\{(\sigma(1), \sigma(2), \dots, \sigma(n)) : \sigma \in \Sigma_n\}.$$

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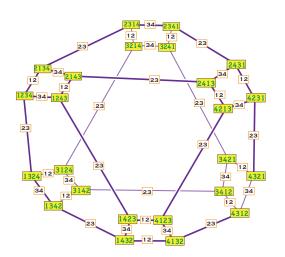
$$\mathbf{i} = (i, i + 1)$$
. Hexagonal faces are $\mathbf{i}(\mathbf{i} + 1)\mathbf{i}(\mathbf{i} + 1)\mathbf{i}(\mathbf{i} + 1)$.

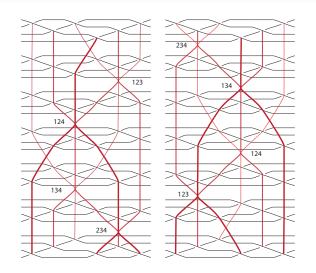
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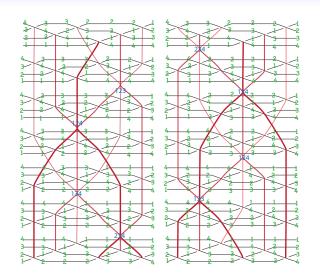
$$\{(\sigma(1), \sigma(2), \dots, \sigma(n)) : \sigma \in \Sigma_n\}.$$

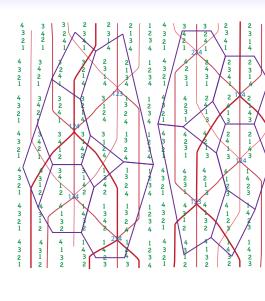
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1 2 3 4 1 2 3 4 1 2 3 4 1 2 3 4 1 2 3 4 1 2 3 4

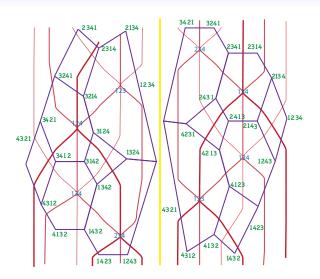
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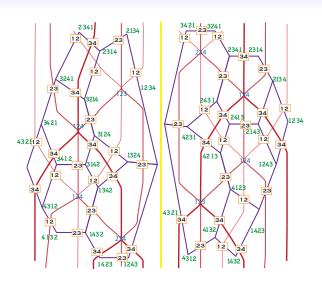
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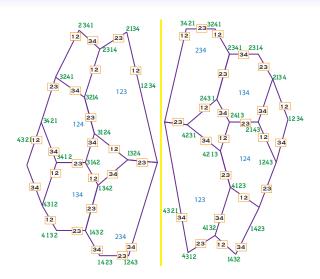
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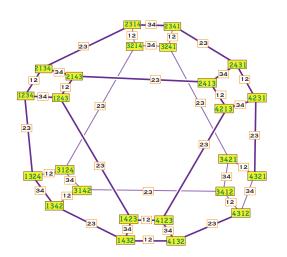
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2 4 3

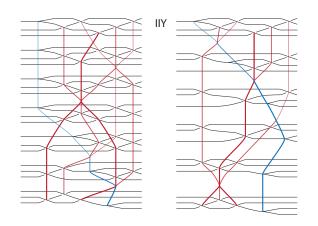


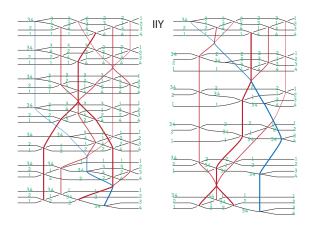


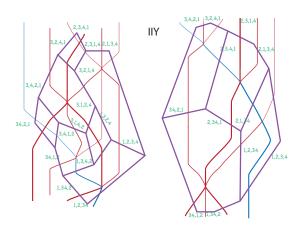


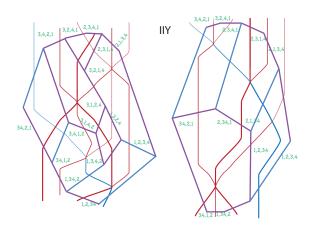


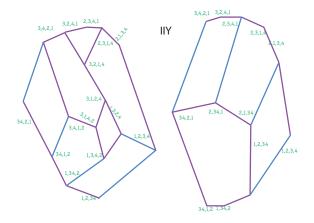
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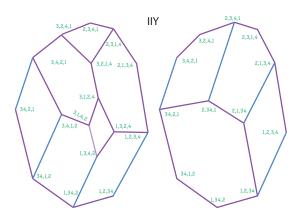


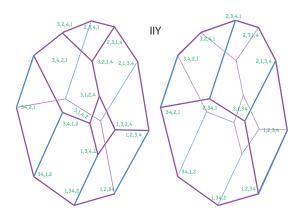


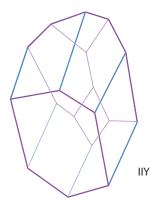


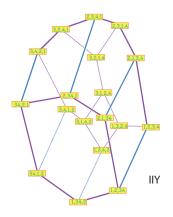


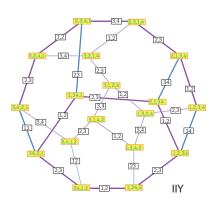












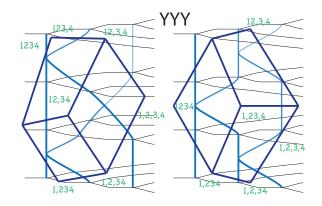
Before being in Asia, I thought that these polytopes were new.

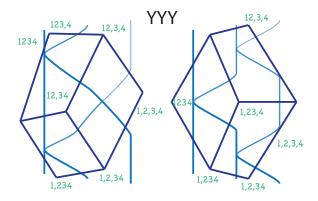
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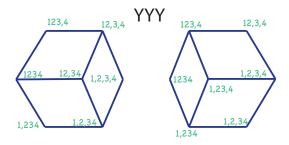
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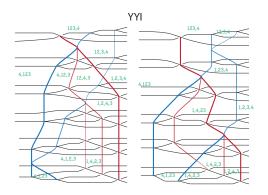
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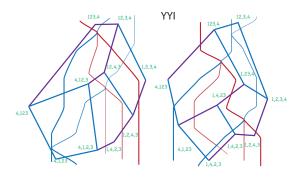


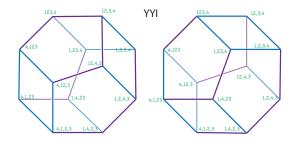


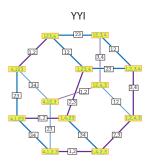


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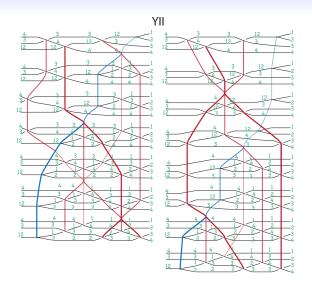


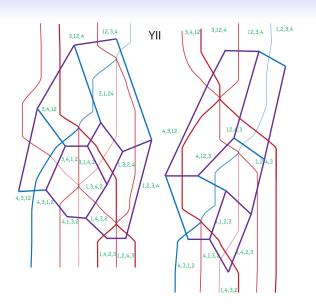


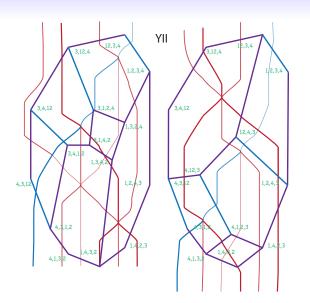


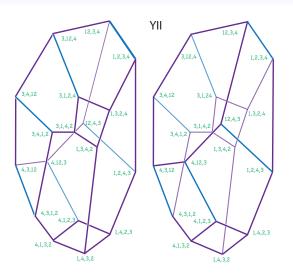


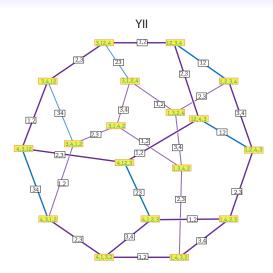
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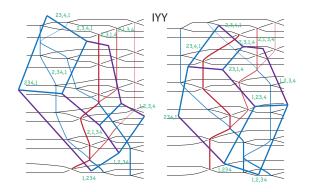


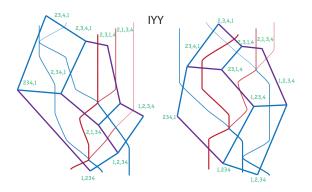


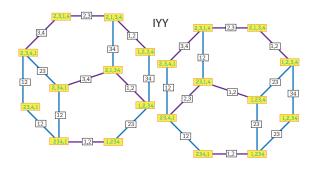


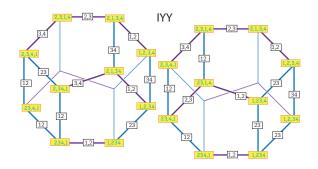


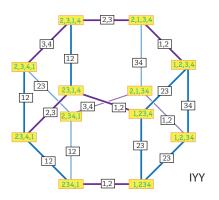
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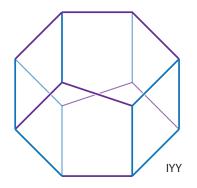




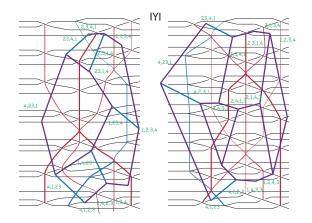


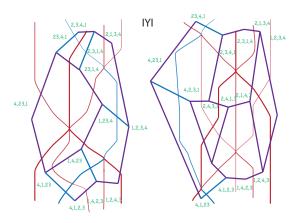


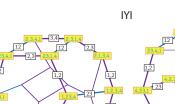


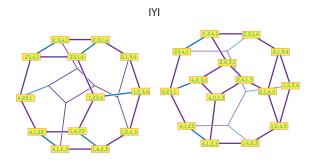


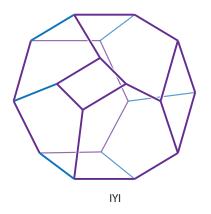
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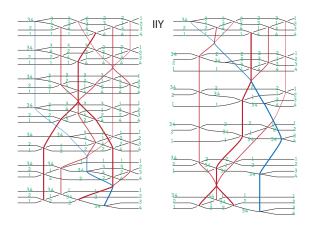


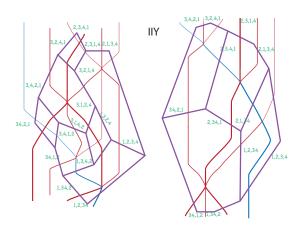
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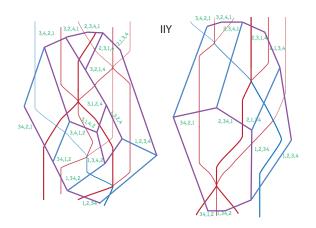


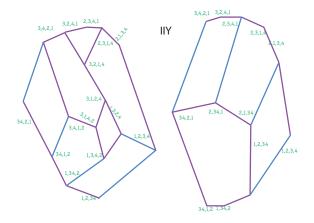


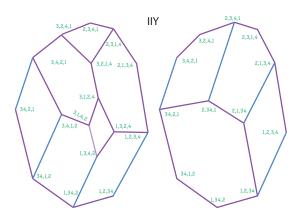
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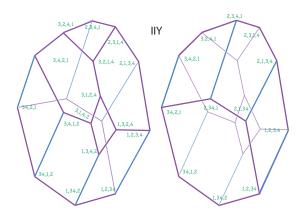


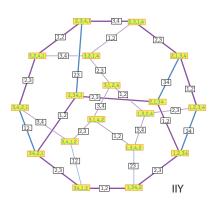


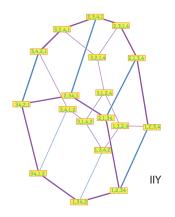


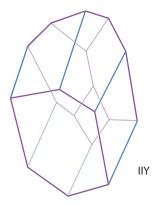


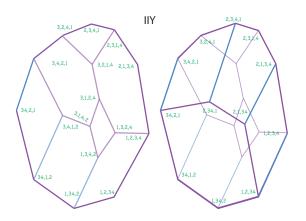




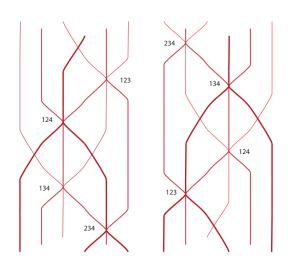








Next we'll use the graphical structure to formulate a series of Abstract tensor equations.

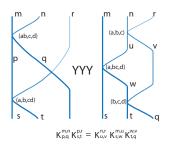


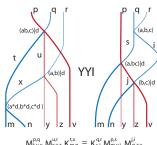
One of these equations is the Zamolodchikov tetrahedral equation.

$$S_{123}S_{124}S_{134}S_{234} = S_{234}S_{134}S_{124}S_{123}.$$

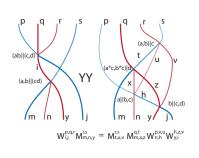
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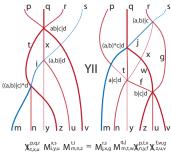
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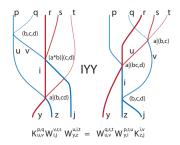


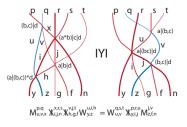


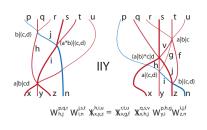
 $M_{t,u,v}^{p,q} \ M_{x,y,z}^{u,r} \ K_{m,n}^{t,x} = \ K_{s,i}^{q,r} \ M_{m,y,j}^{p,s} \ M_{n,z,v}^{j,i}$

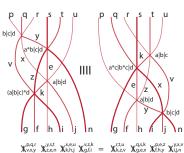












In 3-D

Α	$Y_{j}^{\ell,n}Y_{i}^{j,k}=Y_{p}^{n,k}Y_{i}^{\ell,p}$
ΥI	$Y^{a,b}_dX^{d,c}_{e,f} = X^{b,c}_{c,h}X^{a,c}_{e,g}Y^{g,h}_f.$
ΙΥ	$X_{d,g}^{a,b}X_{h,f}^{g,c}Y_e^{d,h}=Y_i^{b,c}X_{e,f}^{a,i}.$
III	$\left X_{d,e}^{a,b} X_{i,h}^{e,c} X_{f,g}^{d,i} = X_{j,k}^{b,c} X_{f,e}^{a,j} X_{g,h}^{e,k} \right $

$$\begin{aligned} \mathsf{Y}^{a,b}_c &= \left\{ \begin{array}{ll} 1 & \text{if } c = ab, \\ 0 & \text{otherwise;} \end{array} \right. \\ \mathsf{X}^{a,b}_{c,d} &= \left\{ \begin{array}{ll} 1 & \text{if } c = b \ \& \ d = b^{-1}ab, \\ 0 & \text{otherwise.} \end{array} \right. \end{aligned}$$

In 4-D

YYY	$K_{p,q}^{m,n}K_{s,t}^{p,r}=K_{u,v}^{n,r}K_{s,w}^{m,u}K_{t,q}^{w,v}$
YYI	$M^{p,q}_{t,u,v}M^{u,r}_{x,y,z}K^{t,x}_{m,n}=K^{q,r}_{s,i}M^{p,s}_{m,y,j}M^{j,i}_{n,z,v}$
YY	$W_{i,j}^{p,q,r}M_{m,n,y}^{i,s}=M_{t,u,v}^{r,s}M_{m,x,z}^{q,t}W_{n,h}^{p,x,u}W_{y,i}^{h,z,v}$
YII	$\left \begin{array}{c} \mathbf{X}_{t,x,v}^{p,q,r} \mathbf{M}_{y,u,v}^{x,s} \mathbf{M}_{m,n,z}^{t,i} = \mathbf{M}_{j,x,g}^{r,s} \mathbf{M}_{m,t,x}^{q,j} \mathbf{X}_{n,y,f}^{p,t,x} \mathbf{X}_{z,u,v}^{f,w,g} \end{array} \right $
IYY	$K^{p,q}_{u,v}W^{v,r,s}_{i,j}W^{u,i,t}_{y,z} = W^{q,s,t}_{u,v}W^{p,r,u}_{y,i}K^{i,v}_{z,j}$
IYI	$\left \begin{array}{c} M_{u,v,x}^{p,q} X_{i,j,n}^{x,r,s} X_{h,g,f}^{v,j,t} W_{y,z}^{u,i,h} = W_{u,v}^{q,s,t} X_{y,i,j}^{p,r,u} M_{z,f,n}^{j,v} \end{array} \right $
IIY	$\left \begin{array}{c} W_{h,j}^{p,q,r} W_{i,n}^{j,s,t} X_{x,y,z}^{h,i,u} = X_{v,g,f}^{r,t,u} X_{x,h,j}^{q,s,v} W_{y,i}^{p,h,g} W_{z,n}^{i,j,f} \end{array} \right $
IIII	$\left \begin{array}{c} \mathbf{X}_{v,x,y}^{p,q,r} \mathbf{X}_{z,e,n}^{y,s,t} \mathbf{X}_{k,h,j}^{x,e,u} \mathbf{X}_{g,f,i}^{v,z,k} = \mathbf{X}_{k,z,v}^{r,t,u} \mathbf{X}_{g,e,x}^{q,s,k} \mathbf{X}_{f,h,y}^{p,e,z} \mathbf{X}_{i,j,n}^{y,x,v} \end{array} \right $

$$\mathsf{K}^{p,q}_{r,s} = \left\{ \begin{array}{l} 1 \text{ if } \exists \ a,b,c \text{ s.t.} \\ p = ((ab,c),0|0), \quad q = ((a,b),0|0), \\ r = ((a,bc),0|0), \& \ s = ((b,c),0|0). \\ 0 \text{ otherwise;} \end{array} \right.$$

$$\mathsf{M}^{i,j}_{p,q,r} = \left\{ \begin{array}{l} 1 \text{ if } \exists \ a,b,c \text{ s.t.} \\ i = ((0,0),ab|c), \quad j = ((a,b),0|0), \\ p = ((a,b) \lhd c,0|0), \quad q = ((0,0),a|c), \\ \& \ r = ((0,0),b|c), \\ 0 \text{ otherwise;} \end{array} \right.$$

$$\mathsf{W}_{p,q}^{i,j,\ell} = \left\{ \begin{array}{l} 1 \text{ if } \exists \ a,b,c \text{ s.t.} \\ i = ((b,c),0|0), \quad j = ((0,0),(a \lhd b)|c), \\ \ell = ((0,0),a|b), \\ p = ((0,0),a|(bc)), \quad \& \ q = ((b,c),0|0), \\ 0 \text{ otherwise;} \end{array} \right.$$

$$\mathbf{X}_{s,t,u}^{p,q,r} = \begin{cases} 1 \text{ if } \exists \ a,b,c \text{ s.t.} \\ p = ((0,0),b|c), \quad q = ((0,0),(a \triangleleft b)|c), \\ r = ((0,0),a|b), \\ s = ((0,0),(a|b) \triangleleft c), \quad t = ((0,0),a|c), \\ \& \ u = ((0,0),b|c), \\ 0 \text{ otherwise;} \end{cases}$$

where, e.g., $a \triangleleft c = c^{-1}ac$, $(a, b) \triangleleft c = (a \triangleleft c, b \triangleleft c)$, and $(a|b) \triangleleft c = (a \triangleleft c)|(b \triangleleft c)$

These tensors form a solution set over a module whose basis is determined by the underlying algebraic structure precisely because $\partial \circ \partial = 0$ in the chain complex.

Thanks

Thank you for your attention!